## CHAPTER 1 MATLAB EXERCISES

1. Consider the linear system of Example 7 in Section 1.2.

$$x - 2y + 3z = 9$$

$$-x + 3y = -4$$

$$2x - 5y + 5z = 17$$

- (a) Use the MATLAB command **rref** to solve the system.
- (b) Let A be the coefficient matrix of the system, and B the right-hand side.

$$A = \begin{bmatrix} 1 & -2 & 3 \\ -1 & 3 & 0 \\ 2 & -5 & 5 \end{bmatrix} \qquad B = \begin{bmatrix} 9 \\ -4 \\ 17 \end{bmatrix}$$

Use the MATLAB command A\B to solve the system.

2. Enter the matrix

$$A = \begin{bmatrix} -3 & 2 & 4 & 5 & 1 \\ 3 & 0 & 2 & -2 & 0 \\ -9 & 4 & 6 & 12 & 2 \end{bmatrix}$$

Use the MATLAB command rref(A) to find the reduced row-echelon form of A. What is the solution to the linear system represented by the augmented matrix A?

3. Solve the linear system

$$16x - 120y + 240z - 140w = -4$$

$$-120x + 1200y - 2700z + 1680w = 60$$

$$240x - 2700y + 6480z - 4200w = -180$$

$$-140x + 1680y - 4200z + 2800w = 140$$

You can display more significant digits of the answer by typing format long before solving the system. Return to the standard format by typing format short.

4. Use the MATLAB command rref(A) to determine which of the following matrices are rowequivalent to

$$B = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 5 & 6 & 7 & 8 \\ 9 & 10 & 11 & 12 \end{bmatrix}.$$

(a) 
$$\begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 0 & -1 & -2 \\ 0 & 1 & 2 & 3 \end{bmatrix}$$

(b) 
$$\begin{bmatrix} 1 & 3 & 2 & 4 \\ 5 & 6 & 7 & 8 \\ 9 & 10 & 11 & 12 \end{bmatrix}$$

(a) 
$$\begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 0 & -1 & -2 \\ 0 & 1 & 2 & 3 \end{bmatrix}$$
 (b) 
$$\begin{bmatrix} 1 & 3 & 2 & 4 \\ 5 & 6 & 7 & 8 \\ 9 & 10 & 11 & 12 \end{bmatrix}$$
 (c) 
$$\begin{bmatrix} 12 & 11 & 10 & 9 \\ 4 & 3 & 2 & 1 \\ 8 & 7 & 6 & 5 \end{bmatrix}$$

5. Let A be the coefficient matrix, and B the right-hand side of the linear system of equations

$$3x + 3y + 12z = 6$$

$$x + y + 4z = 2$$

$$2x + 5y + 20z = 10$$

$$-x + 2y + 8z = 4$$
.

Enter the matrices A and B, and form the augmented matrix C for this system by using the MATLAB command  $C = [A \ B]$ . Solve the system using rref.

**6.** The MATLAB command **polyfit** allows you to fit a polynomial of degree n-1 to a set of n data points in the plane

$$(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n).$$

Find the fourth-degree polynomial that fits the five data points of Example 2 in Section 1.3 by letting

$$x = \begin{bmatrix} -2 \\ -1 \\ 0 \\ 1 \\ 2 \end{bmatrix} \quad y = \begin{bmatrix} 3 \\ 5 \\ 1 \\ 4 \\ 10 \end{bmatrix}$$

and entering the MATLAB command polyfit(x,y,4).

- 7. Find the second-degree polynomial that fits the points (1, -2), (2, 4), (-4, -6).
- **8.** Find the sixth-degree polynomial that fits the seven points (0,0), (-1,4.5), (-2,133), (-3, 1225.5), (1, -0.5), (2, 3), (3, 250.5).
- 9. The following table gives the world population in billions for five different years.

Year	Population (in billions)
1960	3.0
1970	3.7
1975	4.1
1980	4.5
1985	4.8

Use p=polyfit(x,y,4) to fit the fourth-degree polynomial to this data. Then use f=polyval(p,1990)to estimate the world population for the year 1990. (The actual world population in 1990 was 5.3 billion.)